

# Group Theory Applications: Infra-red Spectral Assignment

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## Abstract

Group theory principles were applied and the transformation of the  $x$ ,  $y$ ,  $z$  vectors on each atom caused by symmetry operations were observed to obtain the  $3N$  basis vector representations  $\mathcal{B}N$  of  $\text{NiCl}_4$ ,  $\text{Al}_2\text{Cl}_6$  and  $\text{Fe}(\text{CO})_5$ . The identified infra-red active modes and Raman active modes were then assigned to the experimental spectral frequencies by using the projection operator method.

**Keywords:** Vibrational mode, vibrational spectrum, infra-red, Raman spectrum, symmetry, group theory, projection operator, spectral frequency assignment.

## Introduction

The number, types and the selection rules for vibrational transitions may be determined solely by reference to symmetry properties of molecules (Thomas 1974). Such symmetry simplifies the analysis of vibrational modes and vibrational spectra (Alberty and Daniels 1979). Molecular symmetry allows prediction of its infra-red or Raman spectrum; and *vice versa* (Ferraro and Ziomek 1975). The vibrational modes of a molecule may be classified into various types, such as bond stretches, and bond angle deformations. It is possible to determine the number and symmetry species of each type.

Continued interest in the field is shown by the appearance of many publications such as Buchachenko and Stepanov (1996); Eryomin *et al.* (1996 & 2000); and Scherbinin *et al.* (1996).

Group theory by itself cannot predict the frequency of a particular vibration, but fairly accurate guesses can be made when combined with accumulated experiences of molecular spectroscopists (Cotton 1971; Kyi 1990).

The prediction requires a number of molecular structural parameters, such as bond lengths and bond angles, in addition to a knowledge of appropriate force constants.

Then Wilson's F and G matrix method is applied after constructing the required symmetry adapted linear combinations (SALC). (Wilson *et al.* 1955).

In principle the vibrational spectrum of any molecule can be analyzed to give specific frequency assignment to every vibrational mode. But in practice, several complicating factors must be taken into account. Factors such as combination bands, difference bands and overtone bands caused by combination of fundamental vibrations; ambiguities with respect to molecular or ionic structure (Davidson 1971); accidental degeneracy; and Fermi resonance (Siebrt 1966).

## Vibrational Mode Assignment of Some Molecules and Ions

### Nickel Tetrachloride Ion

For vibrational mode classification, the normal modes are expressed as functions of a set of internal displacement vectors which yield information on bond stretching and bond bending contributions to different symmetry normal modes (Cotton 1971). The projection operator method is a very powerful method for explicit information on

vector bases for irreducible representations (Wilson *et al.* 1955).

The ion has a square planar structure with a nickel ion at the center of a square plane, surrounded by four chloride ions at the corners. Hence it has a  $D_{4h}$  symmetry (Kyri and Win 2001). The four Ni-Cl bonds which lie in a square planar structure of the nickel tetrachloride ion can stretch and contract in various combinations and are designated as bond stretching internal displacement vectors  $v_1, v_2, v_3$  and  $v_4$ .

The same four Ni-Cl bonds can move above and below the plane of the ion structure, giving rise to four out-of-plane deformation vectors  $d_1, d_2, d_3$ , and  $d_4$ , another set of internal displacement vectors.

The four Cl-Ni-Cl bond angles can expand and contract, giving yet another set of internal displacement vectors  $\delta_1, \delta_2, \delta_3$ , and  $\delta_4$  called in-plane deformation vectors.

The  $\Gamma_{str.}$  is found by using the above bond stretching internal displacement vectors  $v_1, v_2, v_3$  and  $v_4$  as basis. By applying the same procedure as before (Kyri and Win 2001). The irreducible representation obtained from the  $D_{4h}$  point group tables, yield the following result.

$$\Gamma_{str.} = A_{1g} \oplus B_{1g} \oplus E_u \dots\dots\dots(1)$$

Similarly  $\Gamma_{opd}$  is found by using the above four out-of-plane deformation internal displacement vectors  $d_1, d_2, d_3$ , and  $d_4$  as basis.

$$\Gamma_{opd} = E_g \oplus A_{2u} \oplus B_{2u} \dots\dots\dots(2)$$

$\Gamma_{3N}$  (genuine vibrations) does not contain  $E_g$  (Win and Kyri 2000), hence it must correspond to a pair of redundant coordinates.  $E_g$  is thus neglected.

$$\Gamma_{opd} = A_{2u} \oplus B_{2u} \dots\dots\dots(3)$$

$\Gamma_{ipd}$  is obtained by using the  $\delta_1, \delta_2, \delta_3$ , and  $\delta_4$  as basis.

$$\Gamma_{ipd} = A_{1g} \oplus B_{1g} \oplus E_u \dots\dots\dots(4)$$

The  $A_{1g}$  is redundant as all four angles increasing or decreasing simultaneously in a plane is physically impossible. Hence it is neglected. Thus:

$$\Gamma_{ipd} = B_{1g} \oplus E_u \dots\dots\dots(5)$$

In some cases, such as NiCl bond stretches, fundamental modes may be found by applying projection operators P.

### Stretching Modes

The operation of the projection operators of  $A_{1g}, B_{1g}$  and  $E_u$  symmetries (Equation 1) on  $v_1$  yield the following:

$$\begin{aligned} P[A_{1g}]v_1 &= v_1 + v_2 + v_4 + v_3 + v_1 + v_3 + \\ &\quad v_2 + v_4 + v_3 + v_2 + v_4 + v_1 \\ &= 4v_1 + 4v_2 + 4v_3 + 4v_4 \\ &= v_1 + v_2 + v_3 + v_4 \dots\dots\dots(6) \end{aligned}$$

$$P[B_{1g}]v_1 = v_1 - v_2 + v_3 - v_4 \dots\dots\dots(7)$$

$$P[E_u]v_1 = v_1 - v_3 \dots\dots\dots(8)$$

Equation 6 shows that the  $A_{1g}$  mode includes simultaneous equal amplitude bond stretching of all four bonds.

Equation 7 shows that the  $B_{1g}$  modes has one pair of bonds ( $v_1$  &  $v_3$ ) are out of phase by  $\pi$  from another pair of bonds ( $v_2$  &  $v_4$ ) i.e. while one pair is stretching the other pair is contracting.

Equation 8 shows that in the  $E_u$  mode the pair of bonds ( $v_2$  &  $v_4$ ) do not vibrate while ( $v_1$  &  $v_3$ ) are in opposite phase. Since the  $E_u$  mode is doubly degenerate it will contain two fundamental modes. The reduction of  $E_u$  will yield two representations involving complex numbers  $e$  and  $e^*$  (complex conjugate), from which the two true fundamental modes can be determined.

### Out-of-plane Deformation

$$P[A_{2u}] d_1 = d_1 + d_2 + d_3 + d_4 \dots\dots\dots (9)$$

$$P[B_{2u}] d_1 = d_1 - d_2 + d_3 - d_4 \dots\dots\dots (10)$$

Equation 9 shows that all four bonds simultaneously bend upwards from the plane, in-phase and to the same extent. Equation 10 shows bonds 1 and 2 bend upwards while 2 and 4 bend downwards to the same extent.

### ***In-plane Deformation***

$$P[A_{2u}] \delta_1 = \delta_1 + \delta_2 + \delta_3 + \delta_4 \dots\dots\dots(11)$$

$$P[B_{2g}] \delta_1 = \delta_1 - \delta_2 + \delta_3 - \delta_4 \dots\dots\dots(12)$$

$$P[E_u] \delta_1 = \delta_1 - \delta_3 \dots\dots\dots(13)$$

Equation 11 shows the simultaneous expansion of all four angles. It is physically impossible and is therefore redundant. Equation 12 shows that the pair of angles ( $\delta_1$  &  $\delta_3$ ) expand while the other pair of angles ( $\delta_2$  &  $\delta_4$ ) contract, i.e. elongation of a pair of two opposing sides of the square planar ion structure at the same time when the other pair of two opposing sides is contracting. Equation 13 shows that angle  $\delta_1$  expands while angle  $\delta_3$  contracts and vice versa. In other words when angle  $\delta_1$  expands the side extending that angle expands while the side extending angle  $\delta_3$  contracts; and when angle  $\delta_1$  contracts the side extending that angle contracts while the side extending angle 3 expands.

### **Aluminum Chloride**

The molecule has a square planar shape with two chlorine - Cl and two aluminum - Al atoms at alternate corners. Each of the two aluminum atoms have two other chlorine atoms attached, forming  $AlCl_2$  groups which extend outside the base square plane. Thus the molecule has a  $D_{2h}$  symmetry (Win and Kyi 2001).

The four sides of the square planar base are designated as bond stretching internal displacement vectors  $v_1, v_2, v_3$  and  $v_4$ . The four Al-Cl bonds extending outside the square planar base are

labeled  $v_5, v_6, v_7$  and  $v_8$ . These describe the stretching modes.

The angles surrounding one Al atom, on one corner of the square planar base, are denoted as  $\delta_1, \delta_2, \delta_3$ , and  $\delta_4$ , starting from the inner angle going in a clockwise direction. Similar angles  $\delta_5, \delta_6, \delta_7$ , and  $\delta_8$  are defined for the angles surrounding the other Al atom. The two angles Al-Cl-Al on opposite corners of the square planar base are  $\delta_9$  and  $\delta_{10}$ . These constitute the in-plane internal displacement vectors.

The eight bonds, four on each Al atom, can move up and down from the base plane. These angles are denoted  $d_1, d_2, d_3, d_4, d_5, d_6, d_7$ , and  $d_8$ . The projection operators are applied as before and the results obtained are shown in Table 1.

### **Iron Carbonyl**

The molecule has a triangular base with Fe at the center and three carbon atoms at the three apexes. Each of the carbon atoms is bonded to an oxygen atom forming a carbonyl group  $>C=O$ . Thus, there are three carbonyl groups at the apexes. In addition there are two carbonyl groups outside the base plane, one above and one below the base plane. It belongs to the  $D_{3h}$  point group (Cotton *et al.* 1958; Ware 1970).

The Fe-C bonds in the base plane are designated as  $v_1, v_2$ , and  $v_3$ . The associated carbonyl bonds are designated as  $v_4, v_5$ , and  $v_6$ . The Fe-C bonds above and below the base plane are designated as  $v_7$  and  $v_8$ ; and the associated carbonyl bonds are designated as  $v_9$  and  $v_{10}$ .

The three angles surrounding the Fe atom in the base plane are named  $\delta_1, \delta_2$ , and  $\delta_3$ . The angles on each side of the three carbon atoms in the apex carbonyl groups are called  $\delta_4$  and  $\delta_5; \delta_6$  and  $\delta_7$ ; and  $\delta_8$  and  $\delta_9$ . These are the in-plane bending vectors.

The three Fe-C bonds in the base plane  $d_1$ ,  $d_2$ , and  $d_3$  and the three  $>C=O$  bond  $d_4$ ,  $d_5$ , and  $d_6$  are out-of-plane bending vectors.

The projection operators are applied as before and the results obtained are shown in table 2. It is interesting to note that application of the projection operator  $P[E']$  on  $\delta_4$  annihilates  $\delta_5$ ,  $\delta_7$ , and  $\delta_9$  out of a six member set of vectors  $\{\delta_4, \delta_6, \delta_8, \delta_5, \delta_7, \delta_9\}$ . The same operator  $P[E']$  on  $\delta_5$  annihilates  $\delta_4$ ,  $\delta_6$ , and  $\delta_8$ . This is because the sub-sets  $\{\delta_5, \delta_7, \delta_9\}$  and  $\{\delta_4, \delta_6, \delta_8\}$  are not independent with respect to  $C_2$  and  $\sigma_v$ . Thus the operator  $P[E']$  is applied to both subsets. Hence it is advisable to be on the look out for cases where some elements of a basis set disappear on application of a projection operator.

## Frequency Assignment

Group theory can be used up to this stage only. It can only reveal the number and symmetry types of the different possible modes. For assignment of known frequencies theoretical calculations using F and G matrices, based on molecular properties such as group-masses, bond strengths and force constants, are required. The calculations yield frequencies for specific modes. The experimental frequency nearest to the calculated frequency is assigned that mode. Frequency assignment of  $Al_2Cl_6$  modes is shown in Table 3 (Klemperer 1956).

## Conclusion

The difficulty of vibrational analysis increases with structural complexity. This is partly because structural complexity makes complete identification of internal coordinates (true basis vectors) difficult. Some coordinates can often be missed out.

Thus it is advisable to check that:

$$\Gamma_{\text{vibration (genuine)}} = \sum_i \Gamma_i, \text{ where } \Gamma_i \text{ are}$$

$\Gamma_{\text{str}}, \Gamma_{\text{ipd}}, \Gamma_{\text{opd}} \dots \text{ etc...}$

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Table 1. Fundamental modes of  $\text{Al}_2\text{Cl}_6$ 

Mode	Projector	Projected vector	Remarks		
Stretching	$2A_g$	$P[A_g]v_1$	$v_1 + v_2 + v_3 + v_4$	in-phase stretch	
		$P[A_g]v_5$	$v_5 + v_6 + v_7 + v_8$		
	$2B_{1g}$	$P[B_{1g}]v_1$	$v_1 - v_2 + v_3 - v_4$	two opposing sets	
		$P[B_{1g}]v_5$	$v_5 - v_6 + v_7 - v_8$		
	$2B_{2u}$	$P[B_{2u}]v_1$	$v_1 + v_2 - v_3 - v_4$	redundant mode	
		$P[B_{2u}]v_5$	$v_5 + v_6 - v_7 - v_8$		
$2B_{3u}$	$P[B_{3u}]v_1$	$v_1 - v_2 - v_3 + v_4$			
	$P[B_{3u}]v_5$	$v_5 - v_6 - v_7 + v_8$			
In-plane bend	$4A_g$	$P[A_g]\delta_1$	$\delta_1 + \delta_7$		
		$P[A_g]\delta_6$	$\delta_9 + \delta_{10}$		
		$P[A_g]\delta_5$	$\delta_3 + \delta_5$		
		$P[A_g]\delta_9$	$\delta_2 + \delta_4 + \delta_6 + \delta_8$		
	$1B_{1g}$	$P[B_{1g}]\delta_1$	0		
		$P[B_{1g}]\delta_6$	$\delta_4 + \delta_6 - \delta_2 - \delta_8$		
		$P[B_{1g}]\delta_5$ & $P[B_{1g}]\delta_9$	0		
	$2B_{2u}$	$P[B_{2u}]\delta_1$	0		
		$P[B_{2u}]\delta_6$	$\delta_2 - \delta_4 + \delta_6 - \delta_8$		
		$P[B_{2u}]\delta_5$	0		
		$P[B_{2u}]\delta_9$	$\delta_9 - \delta_{10}$		physically impossible
	$3B_{3u}$	$P[B_{3u}]\delta_1$	$\delta_1 - \delta_7$		physically impossible
		$P[B_{3u}]\delta_1$	$\delta_6 + \delta_8 - \delta_2 - \delta_4$		
		$P[B_{3u}]\delta_1$	$\delta_5 - \delta_3$		
		$P[B_{3u}]\delta_1$	0		
	Out-of-plane bend	$2B_{2g}$	$P[B_{2g}]d_1$		$d_1 + d_2 - d_5$
$P[B_{2g}]d_3$			$d_3 - d_4 + d_8$	physically impossible	
$2B_{3g}$		$P[B_{3g}]d_1$	$d_1 - d_2 + d_5$		
		$P[B_{3g}]d_3$	$d_3 + d_4 - d_8$	physically impossible	
$2A_u$		$P[A_u]d_1$	$d_1 - d_2 - d_5$		
		$P[A_u]d_3$	$d_3 - d_4 - d_8$	physically impossible	
$2B_{1u}$		$P[B_{1u}]d_1$	$d_1 + d_2 + d_5$		
		$P[B_{1u}]d_3$	$d_3 + d_4 + d_8$		

Table 2. Fundamental modes of Fe (CO)<sub>5</sub>

Mode	Projector	Projected vector	Remarks	
Stretching	4A <sub>1</sub> '	P[A <sub>1</sub> ']v <sub>1</sub>	v <sub>1</sub> + v <sub>2</sub> + v <sub>3</sub>	non-redundant
		P[A <sub>1</sub> ']v <sub>8</sub>	v <sub>8</sub> + v <sub>9</sub>	physically possible
		P[A <sub>1</sub> ']v <sub>7</sub>	v <sub>7</sub> + v <sub>10</sub>	modes
		P[A <sub>1</sub> ']v <sub>4</sub>	v <sub>4</sub> + v <sub>5</sub> + v <sub>6</sub>	
2E'	P[E']v <sub>1</sub>	2v <sub>1</sub> - v <sub>2</sub> - v <sub>3</sub>	non-redundant	
	P[E']v <sub>8</sub> & P[E']v <sub>7</sub>	0	possible modes	
	P[E']v <sub>4</sub>	2v <sub>4</sub> - v <sub>5</sub> - v <sub>6</sub>		
2A <sub>2</sub> "	P[A <sub>2</sub> " ]v <sub>1</sub>	0	non-redundant	
	P[A <sub>2</sub> " ]v <sub>8</sub>	v <sub>8</sub> - v <sub>9</sub>	possible modes	
	P[A <sub>2</sub> " ]v <sub>7</sub>	v <sub>7</sub> - v <sub>10</sub>		
	P[A <sub>2</sub> " ]v <sub>4</sub>	0		
In-plane bend	2A <sub>1</sub> '	P[A <sub>1</sub> ' ]δ <sub>1</sub>	δ <sub>1</sub> + δ <sub>2</sub> + δ <sub>3</sub>	redundant, impossible
		P[A <sub>1</sub> ' ]δ <sub>4</sub>	δ <sub>4</sub> + δ <sub>5</sub> + δ <sub>6</sub> + δ <sub>7</sub> + δ <sub>8</sub> + δ <sub>9</sub>	ditto
3E'	P[E'] δ <sub>1</sub>	2δ <sub>1</sub> - δ <sub>2</sub> - δ <sub>3</sub>		
	P[E'] δ <sub>4</sub>	2δ <sub>4</sub> - δ <sub>6</sub> - δ <sub>8</sub>		
	P[E'] δ <sub>5</sub>	2δ <sub>5</sub> - δ <sub>7</sub> - δ <sub>9</sub>		
1A <sub>2</sub> '	P[A <sub>2</sub> ' ]δ <sub>1</sub>	0		
	P[A <sub>2</sub> ' ]δ <sub>6</sub>	δ <sub>4</sub> - δ <sub>5</sub> + δ <sub>6</sub> - δ <sub>7</sub> + δ <sub>8</sub> - δ <sub>9</sub>		
Out-of-plane bend	2A <sub>2</sub> "	P[A <sub>2</sub> " ]d <sub>1</sub>	d <sub>1</sub> + d <sub>2</sub> + d <sub>3</sub>	
		P[A <sub>2</sub> " ]d <sub>4</sub>	d <sub>4</sub> + d <sub>5</sub> + d <sub>6</sub>	two modes are same
2E"	P[E" ]d <sub>1</sub>	2d <sub>1</sub> - d <sub>2</sub> - d <sub>3</sub>		
	P[E" ]d <sub>4</sub>	2d <sub>4</sub> - d <sub>5</sub> - d <sub>6</sub>	two modes are same	
Top & bottom	A <sub>1</sub> '	P[A <sub>1</sub> ' ]δ <sub>1</sub>	δ <sub>1</sub> + δ <sub>2</sub> + δ <sub>3</sub> + δ <sub>4</sub> + δ <sub>5</sub> + δ <sub>6</sub>	all are physically
>C=O bend	E'	P[E'] δ <sub>1</sub>	2δ <sub>1</sub> - δ <sub>2</sub> - δ <sub>3</sub> + 2δ <sub>4</sub> - δ <sub>5</sub> - δ <sub>6</sub>	impossible modes

$$\begin{array}{ll}
A_2'' & P[A_2''] \delta_1 \quad \delta_1 + \delta_2 + \delta_3 - \delta_4 - \delta_5 - \delta_6 \\
E'' & P[E''] \delta_1 \quad 2\delta_1 - \delta_2 - \delta_3 - 2\delta_4 + \delta_5 + \delta_6
\end{array}$$


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Table 3. Al<sub>2</sub>Cl<sub>6</sub> Frequencies

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Symmetry of fundamental mode	Experimental frequency / cm <sup>-1</sup>
A <sub>g</sub>	$\nu_1 = 506$
	$\nu_2 = 340$
	$\nu_3 = 217$
	$\nu_4 = 112$
Au	$\nu_5 = \text{---}$
B <sub>1g</sub>	$\nu_6 = 438$
	$\nu_7 = 164$
B <sub>1u</sub>	$\nu_8 = 625$
	$\nu_9 = \text{---}$
	$\nu_{10} = \text{---}$
B <sub>2g</sub>	$\nu_{11} = 606$
	$\nu_{12} = 164$
B <sub>2u</sub>	$\nu_{13} = \text{---}$
	$\nu_{14} = \text{---}$
B <sub>3g</sub>	$\nu_{15} = \text{---}$
B <sub>3u</sub>	$\nu_{16} = 484$
	$\nu_{17} = \text{---}$
	$\nu_{18} = \text{---}$

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